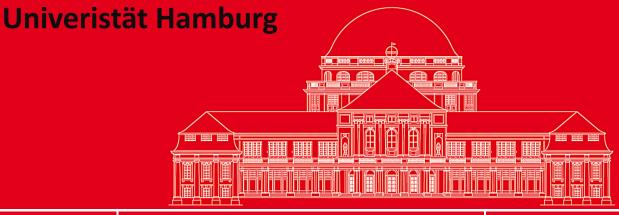


Time on task in collaborative learning. Influence of learning goal orientation and group composition

Jens Siemon, Antonia Scholkmann & Kay-Dennis Boom





Overview

Introduction

How to measure effective learning in collaborative learning situations?

The Multimodal Video- and Audioanalysis (MuVA)

Time on task and goal orientation as research variables

The present study

Research questions

Procedure

Findings

Discussion and further implications



Collaborative learning

- Learning in situations in which the teacher is not constantly present
- High amount of self-directed learning strategies necessary, e. g. problem-analysis, search for solutions, evaluation of solutions, implementation etc.
- Peer-to-peer learning as predominant social form
- ⇒ Peer-influences in collaborative learning not extensively researched yet



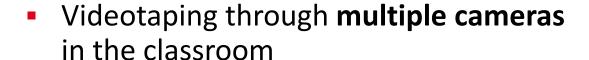
The challenge

How to document and analyse learning in open, collaborative learning situations, with a focus on **peer-to-peer interaction**?



Multimodal Video- and Audioanalysis (MuVA)

(Knigge et al. 2013; Siemon et al. 2015)





- Individualized audiotaping of verbal utterances through portable micro-recorders
- Combination of sources for analysis via Adobe PremierePro
- ⇒ analysis of peer-to-peer behaviour on the micro-level



Time on task in collaborative learning. Influence of learning goal orientation and group composition

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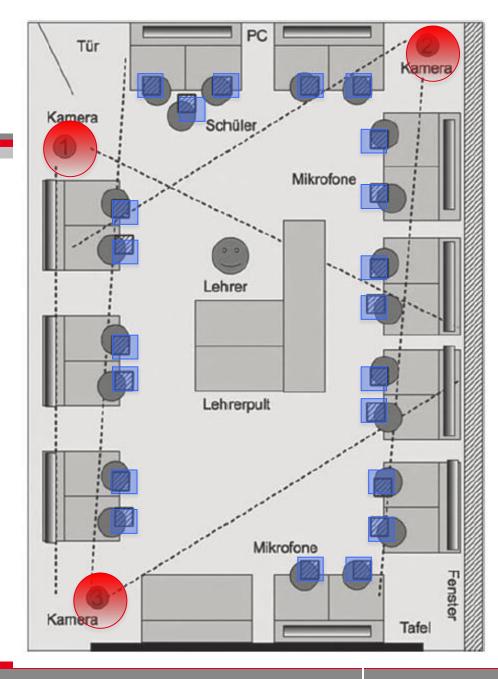
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The dataset

(cf. Knigge et al. 2013a, b)

- N=59 students in a vocational education program (accounting and logistics)
- worked in dyads
- Simulation-based, computersupported collaborative assignment (logistic:challenge, Siemon et al. 2012)
- Per class: 8 hours/class recorded with MuVA (total 24 hours recorded material)





Time on Task (TT)

- Time spent working effectively and successfully on a given assignment (cf. Anderson 1995, Bordhagen & Gettinger 2012)
- Effective predictor of academic performance (cf. van Gog 2012)

TT in collaborative learning

- Decreased amount of direct control through the teacher (cf. Lipowsky 2006)
- Interest into factors that influence students' time on task when teacher is not present



Goal orientation (GO)

- Motivational disposition to orient ones efforts
- Substantial influence on the time on task is assumed (van Gog 2012)

Goal orientation in collaborative learning:

 Not only a students goal orientation has to be considered, but also the learning partner's goal orientation (Knigge, Siemon, Nordstrand, & Stolp, 2013).



Research questions

- How does the goal orientation of a student influence his or her time on task in the open phases of collaborative simulation-based learning?
- How does the goal orientation of the learning partner influence the time on task of a student in the open phases of collaborative simulation-based learning?
- How does the similarity of the goal orientations between a student and his/her learning partner in a dyad relate to the time on task in the open phases of collaborative simulationbased learning?



Procedure 1

- Coding of the collaborative phases in the dataset with the a specially developed coding-manual 'Time on Task (TT)'
- Per student/class: two independent raters
- trained before coding
- not allowed to discuss decisions while coding
- Analysis of inter- and intra-rater agreement



Coding manual TT			
Time-sampling, 10-sec. intervals			
Coding of 4 aspects:			
Focus on/off topic	Subject of conversation	Activity of student	Social form of interaction
Low-inference rating:			
"The aspect is" \Box present \Box not present			



Coding manual TT				
Time-sampling, 10-sec. intervals				
	Coding of 4 aspects:			
FocusSubjectActivitySocial formon/off topicof conversationof studentof interaction				
Low-inference rating:				
"The aspect is" □ present □ not present				
Inter-rater-agreement (Cohen 's κ)				
83 ≤ κ ≤ .89	.63 ≤ κ ≤ .80	.59 ≤ κ ≤ .74	.68 ≤ κ ≤ .78	
<u>Intra-rater agreement (Cohen 's κ)</u>				
.83 ≤ κ ≤ .84	.75 ≤ κ ≤ .80	.63 ≤ κ ≤ .75	.69 ≤ κ ≤ .83	



Procedure 2

Survey of goal orientations with the SELLMO-Scales (Spinath et al., 2002)

Four scales:

- Learning Goal Orientation (LG): Pursuit to extend one's competence
- Achievement Goal Orientation (AG): Pursuit to demonstrate one's competence
- Performance Avoidance Orientation (PA): Pursuit to hide one's own (alleged) incompetence
- Work Avoidance: Pursuit to avoid effort



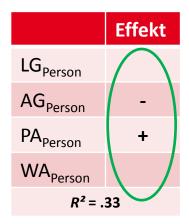
Procedure 3

- RQs 1 & 2: Computation of hierarchical regression models
- **Step 1:** SELLMO-scales, student's values
- Step 2: SELLMO-scales, student's values + learning partner's values
- Relative amount of on-topic behaviour (aspect "focus" form TT manual) as dependent variable
- RQ 3: Correlation analysis
 - Variable 1: Differences on goal orientations measurement values between a student and his/her learning partner
 - Variable 2: Relative amount of on-topic behaviour



Findings (RQs 1 & 2)

Step 1
Student's
values



Step 2
Student's values &
learning partner's values

	Effekt		Effekt	
LG _{Person}		LG _{Partner}	+	
AG _{Person}	-	AG _{Partner}	-	
PA _{erson}	+	PA _{Partner}	+	
WA _{Person}	\ - /	WA _{Partner}	\ - /	
$R^2 = 65$				

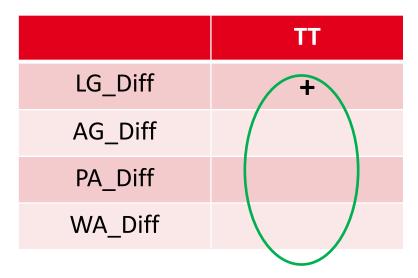
Dependent variable: Relative amount of on-topic behaviour

LG= Learning goal orientation; AG = Achievement goal orientation; PA = Performance goal orientation; WA = Work avoidance orientation

$$R^2_{Modell\,2} > R^2_{Modell\,1}$$



Findings (RQ 3)



p(r) < .05; correlation presented only if r > .30

DIFF: Difference in measure for goal orientation TT: Relative amount of on-topic behaviour

LG= Learning goal orientation; AG = Achievement goal orientation; PA = Performance goal orientation; WA = Work avoidance orientation

Interpretation

The more similar a student and his/her learning partner are with respect to their learning goal motivation, the higher is this student's amount of on-topic behaviour



Discussion I

- Both student's and learning partner's goal orientation predict time on task
- ⇒ Influences congruent with goal orientation theory & previous findings
- ⇒ Explanatory value added through inclusion of partner values is high!



Discussion II

- Specific influence of learning goal orientation on time on task in collaborative learning situations
- ⇒ It is not important, whether a student is highly learning goal oriented himself/herself – what is important is...
 - a) To have a highly learning goal oriented partner
 - b) To be similar to him/her in your own learning goal orientation



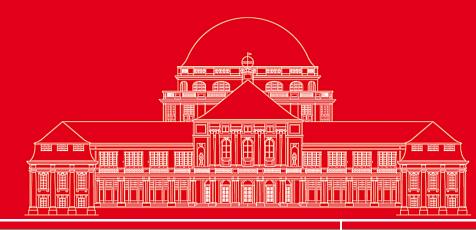
Implications

- ✓ <u>Empirically:</u> Learning partners must be included in analysis of collaborative learning
- ✓ <u>Practically:</u> Teachers and educators should pay attention to group composition aspects
- ✓ <u>Methodologically:</u> MuVA as reliable instrument should be used for analysis of collaborative learning



Thank you for your attention ©

Siemon, J., Scholkmann, A., & Boom, K.-D. (2015, Oktober 9). Time on Task in Collaborative Learning. Influence of Learning Goal Orientation and Group Composition. Paper presented at the ECER/Budapest.





Coding Scheme TT

Focus	Subject	Activity	Social form	Examples		
on topic	Learning time	Active	Alone/silent [4]	Works silently on PC or with paper and pencil; conversations with oneself, mumbling		
[2]	[3]	[2] etc.		etc.		
			In conversation with learning partner(s) [3]	Talks with the learning partner(s) about the task at hand		
			In conversation with teacher [2]	Poses questions towards the teacher/talks with the teacher about the task at hand		
			In conversation with other group [1]	Talks with another group of learners (not learning partners(s) only), asks for help		
		Passive	Alone/silent [4]	Watches/listens to video (as introduction of the learning sequence), watches the learn-		
		[1]	7 (2.51)	ing partner(s) and engages in reflections; conversations with oneself, mumbling etc.		
			In conversation with learning partner(s) [3]	Listens to the learning partner(s), who talk(s) about the topic at hand		
			In conversation with teacher [2]	Listens to the teacher, who talks about the topic at hand		
			In conversation with other group [1]	Listens to another group of learners, who talk about the topic at hand		
	Organisation	Active	Alone/silent [4]	Reads instructions		
	of the learn-	[2]	In conversation with learning partner(s) [3]	Talks with the learning partner(s) about the organization of the learning process		
	ing process				In conversation with teacher [2]	Asks questions/talks with the teacher about the organization of the learning process
	[2]		In conversation with other group [1]	Talks with another group of learners about the organization of the learning process		
		Passive	Alone/silent [4]	Waits for the PC to boot ("please wait" sing on the screen)		
		[1]	In conversation with learning partner(s) [3]	Listens to the learning partner(s), who talks about the organization of the learning		
			, , , , , , , , , , , , , , , , , , ,	process		
			In conversation with teacher [2]	Listens to the teacher who talks about the organization of the learning process		
			In conversation with other group [1]	Listens to another group of learners, who talk about the organization of the learning process		
Off topic	Private	Active	Alone/silent [4]	Plays with mobile etc.		
[1]	[1]	[2]	In conversation with learning partner(s) [3]	Talks with the learning partner(s) about private matters		
			In conversation with teacher [2]	Talks with the teacher about private matters		
			In conversation with other group [1]	Talks with another group of learners about private matters		
		Passive	Alone/silent [4]	Is not involved in the learning process at all, only with him-/herself: bounces on the		
		[1]	, , , , , , , , , , , , , , , , , , , ,	chair, sings to him-/h		
			In conversation with learning partner(s) [3]	Listens to the learnin Listens to the teacher Authentic marker: 2,3,2,3		
			In conversation with teacher [2]	Listens to the teacher Autilentic Indiker. 2,5,2,5		
			In conversation with other group [1]	Listens to another gr		
Unclear [0]	Unclear [0]	Unclear [0]	Unclear [0]	Unclear; also: to many code-switches within on coding interval		

Predictor	ΔR^2	Beta	$SE_{\mathfrak{b}}$	p
Step 1	.33			.001
LG		.21	.02	.166
AG		63	.02	.000
PA		.51	.02	.001
WA		25	.02	.079
Step 2	.32			.000
LG		.23	.01	.062
AG		74	.02	.000
PA		.58	.01	.000
WA		37	.01	.004
LG partner		.32	.02	.013
AG partner		26	.02	.038
PA partner		.33	.01	.007
WA partner		46	.01	.000
Total R ²	.65			

LG=learning goal orientation; AG=achievement goal orientation; PA=performance avoidance orientation; WA=work avoidance orientation; p < .05 **bold**

	r	p
LG_Diff_B	35	.009
PG_Diff_B	24	.052
PA_Diff_B	10	.246
WA_Diff_B	00	.489

LG_Diff_B=difference for learning goal orientation; PG_Diff_B=difference for performance goal orientation; PA_Diff_B=difference for performance avoidance orientation; WA Diff B=difference for work avoidance orientation

ANHANG

Model diagnostics

Normal distribution of residues ✓

- Since *N* > 30 => Central Limit Theorem for both models
- Visual inspection & Shapiro-Wilk Test (n.s.)

Multicollinearity ✓

$$-VIF_{Max} = 1,89 < 10; T_{Min} = 0,52 > 0,2$$

Homoscedasticity ✓

- ■Test after Glejser:
 - $|\operatorname{Res}| = \beta_0 + \beta_i x$ $\rightarrow \beta_i = \text{n.s.}$
 - $|\operatorname{Res}| = \beta_0 + \beta_i V(x) \rightarrow \beta_i = \text{n.s.}$
 - $|\text{Res}| = \beta_0 + \beta_i 1/x \rightarrow \beta_i = \text{n.s.}$
- Visual inspection

Conclusion:

Regression coefficients and & SD have been estimated unbiased